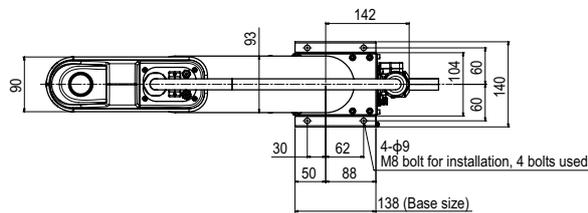


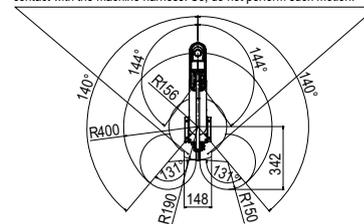


YA	Articulated robots
LCM	Linear conveyor modules
CX	Single-axis robots
Robomity	Motor-less single axis actuator
TRANSERO	Compact single-axis robots
FLIP-X	Single-axis robots
PHASER	Linear motor single-axis robots
XY-X	Cartesian robots
YK-X	SCARA robots
YP-X	Pick & place robots
CLEAN	CLEAN
CONTROLLER	CONTROLLER
INFORMATION	INFORMATION
Orbit/Extra small type	Orbit/Extra small type
Small type	Small type
Large type	Large type
Wall mount/Inverse type	Wall mount/Inverse type
Dust-proof & drip-proof type	Dust-proof & drip-proof type

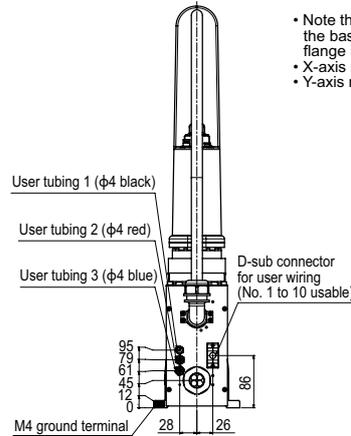
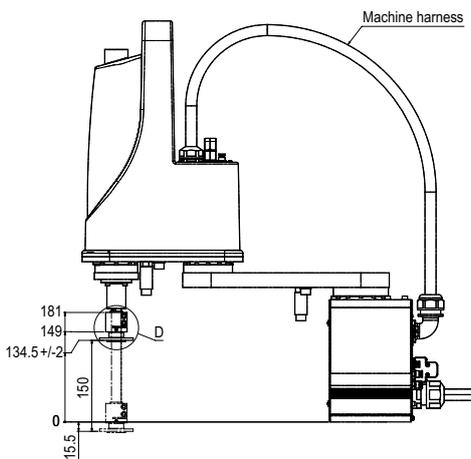
YK400XG Tool flange mount type



If the robot enters the inside of the corner of R190 and dimension 148, the tool flange may be in contact with the base or the arm may be in contact with the machine harness. So, do not perform such motion.



- Note that the robot cannot be used at a position where the base flange or robot cable interferes with the tool flange in the working envelope shown above.
- X-axis mechanical stopper position : 142°
- Y-axis mechanical stopper position : 146°



4-M3 × 0.5 through-hole (No phase relation to R-axis origin.)  
As this hole is intended for the wiring/tubing clamp, do not attach a large load to it.

