YK900XGS

Wall mount / inverse type

- Arm length 900mm
- Maximum payload 20kg

Ordering method

YK900XGS -	[ ]	-	[ ]	-	[ ]	-	[ ]	-	RCX340-4	-	[ ]	-	[ ]	-	[ ]	-	[ ]	-	[ ]	-	[ ]
Model	Installation method Note 1		Z axis stroke		Tool flange		Cable		Controller / Number of controllable axes		Safety standard		Option A (OP.A)		Option B (OP.B)		Option C (OP.C)		Option D (OP.D)		Option E (OP.E)		Absolute battery
	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)		200: 200mm 400: 400mm		No entry: None F: With tool flange		3L: 3.5m 5L: 5m 10L: 10m																

Specify various controller setting items. RCX340 ▶ P.678

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

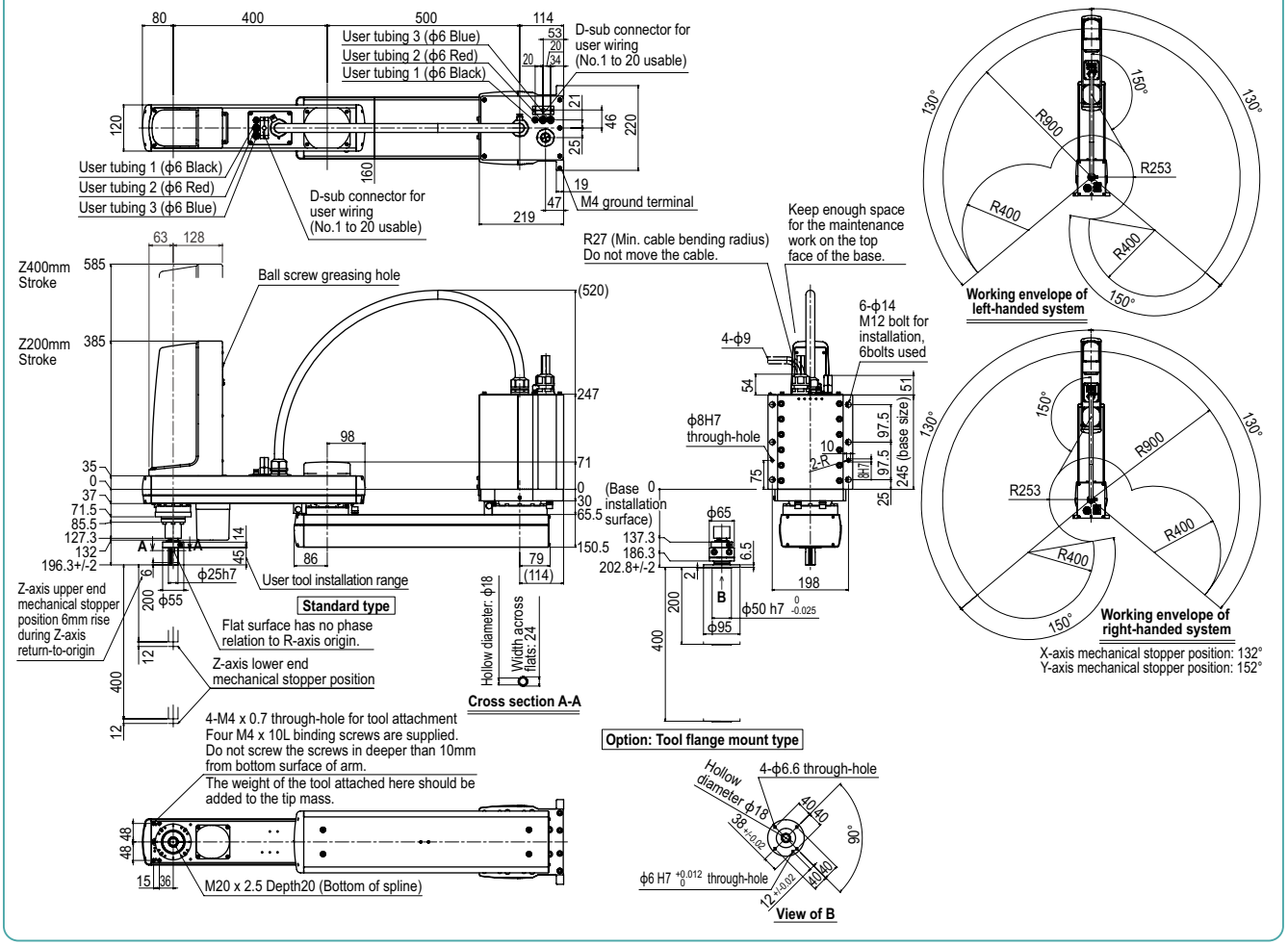
			X-axis	Y-axis	Z-axis		R-axis
Axis specifications	Arm length		500 mm	400 mm	200 mm	400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–		+/-360 °
AC servo motor output			750 W	400 W	400 W		200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled				
		Speed reducer to output	Direct-coupled				
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm		+/-0.004 °
Maximum speed			9.9 m/sec		2.3 m/sec	1.7 m/sec	920 °/sec (wall mount) 480 °/sec (inverse wall mount)
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)				
Standard cycle time: with 2kg payload Note 2			0.49 sec				
R-axis tolerable moment of inertia Note 3			1.0 kgm²				
User wiring			0.2 sq × 20 wires				
User tubing (Outer diameter)			ϕ 6 × 3				
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)				
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m				
Weight			Z axis 200 mm: 54 kg Z axis 400 mm: 56 kg				

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

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