■ Power capacity

Axial current sensor value

Required power supply capacity varies according to the robot type and number of axes. Prepare a power supply using the following table as a general guide.

When connected to 2 axes (Cartesian robot or multi-axis robot)

/ txiai carrent	ochool value	Power capacity (VA)		
X axis	Y axis			
05	05	500		
10	05	700		
10	10	900		
20	05	1500		
20	10	1700		
20	20	2000		
		2400 (HP)		

Motor capacity vs. current sensor table

	Connected motor capacity	Current sensor		
	100W or less	05		
	200W	10		
	400W or more	20		

Note. Motor output of the B14H is 200W but the current

sensor is 05.

Note. Even if axial current sensor values for each axis are interchanged no problem will occur.